

THE PROPAGATION OF THERMAL STRESSES IN AN ELASTIC-PLASTIC BAR

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This paper treats the problem of the propagation of stress waves in a semi-infinite elastic-plastic bar resulting from sudden heating of the free end; moreover, account is taken of the dependence of the coefficient of thermal conductivity on the temperature (i.e. the nonlinear equation of heat conduction will be used), which [1,2] gives rise to a finite velocity of propagation of heat in the bar. The consideration of this fact leads to quantitative features of the elastic solution differing from well-known earlier solutions (e.g. [3]). It will be assumed that the material of the bar is incompressible and linearly elastic; the mechanical properties will be regarded as being independent of the temperature.

1. The solution of the problem leads to the solution of the following system of equations

$$\rho \frac{\partial^2 v}{\partial t^2} = \frac{\partial \sigma}{\partial x} \quad (\text{equation of motion}) \quad (1.1)$$

$$\sigma = E \left(\frac{\partial v}{\partial x} - \alpha \vartheta \right) \quad (\text{equation of state}) \quad (1.2)$$

$$\frac{\partial \vartheta}{\partial t} = \frac{\partial}{\partial x} \left(\lambda \frac{\partial \vartheta}{\partial x} \right) \quad (\text{equation of heat conduction}) \quad (1.3)$$

where σ is the stress, v the displacement, ρ the density, ϑ the temperature, α the coefficient of thermal expansion and λ the coefficient of thermal conductivity. We will assume a power-law dependence of λ on ϑ of the following form

$$\lambda = \lambda_0 \frac{n\alpha^{n-1}}{c_s^{n-1}} \vartheta^{n-1} \quad (n > 1) \quad \left(e_s = \frac{\sigma_s}{E} \right)$$

where σ_s is the yield stress. Then, equation (1.3) can be written as

$$\frac{\partial \vartheta}{\partial t} = \lambda_0 \frac{\alpha^{n-1}}{c_s^{n-1}} \frac{\partial^2 \vartheta^n}{\partial x^2}$$

In the system of dimensionless variables

$$y = \frac{\sqrt{E}}{\lambda_0 \sqrt{\rho}} x, \quad \tau = \frac{E}{\lambda_0 \rho} t, \quad T = \frac{\alpha \vartheta}{c_s}, \quad u = \frac{\sqrt{E}}{\lambda_0 \sqrt{\rho} c_s} v, \quad s = \frac{\sigma}{\sigma_s} \quad (1.4)$$

the initial system of equations assumes the form

$$\frac{\partial^2 u}{\partial \tau^2} = \frac{\partial s}{\partial y}, \quad s = \frac{\partial u}{\partial y} - T, \quad \frac{\partial T}{\partial \tau} = \frac{\partial^2 T^n}{\partial y^2} \quad (1.5)$$

The initial and boundary conditions will be

$$u(y, 0) = 0, \quad \partial u(y, 0) / \partial \tau = 0, \quad s(0, \tau) = 0 \quad (1.6)$$

$$T(y, 0) = 0, \quad T(0, \tau) = T_0 \quad (1.7)$$

For definiteness, we will set $n = 2$ in (1.5). We solve the resulting equations by means of the method of Kármán-Pohlhausen; the solution will be sought in the form

$$T = a_0 + a_1 \frac{y}{l(\tau)} + a_2 \left[\frac{y}{l(\tau)} \right]^2 + \dots \quad (1.8)$$

where $T \equiv 0$ for $y < l(\tau)$, $l(\tau) \rightarrow 0$ as $\tau \rightarrow 0$. In order to simplify the resulting calculations, consideration will be restricted to the first two terms in the expansion (1.8). It can be verified directly, that the calculation of a large number of terms does not change the qualitative picture of the solution for the stresses. Taking condition (1.7) into account, we obtain

$$T = \begin{cases} T_0 [1 - y/l(\tau)], & y \leq l(\tau) \\ 0, & y \geq l(\tau) \end{cases} \quad (1.9)$$

Satisfying the last of equations (1.5) in the mean with respect to y , we have for $l(\tau)$ the equation

$$\int_0^{l(\tau)} \frac{\partial T}{\partial \tau} dy = \int_0^{l(\tau)} \frac{\partial^2 T^2}{\partial y^2} dy$$

Now substituting expression (1.9) for T and carrying out the

integrations, we obtain

$$\frac{1}{2} \frac{dl}{d\tau} = \frac{2T_0}{l(\tau)}, \quad l(0) = 0 \quad (1.10)$$

Hence

$$l(\tau) = \beta \sqrt{\tau} \quad (\beta = 2 \sqrt{2T_0})$$

2. From (1.5) we obtain the equation of motion in terms of the displacements

$$\frac{\partial^2 u}{\partial \tau^2} = \frac{\partial^2 u}{\partial y^2} - Q(y, \tau), \quad Q = \frac{\partial T}{\partial y} \quad (2.1)$$

The solution of this equation in the region bounded by the *Oy*-axis and the bisector $\tau = y$ (Fig. 1) for the initial conditions (1.8) can be given by d'Alembert's formula

$$\begin{aligned} u(B) &= -\frac{1}{2} \iint_{\Delta ABC} Q(\xi, \eta) d\xi d\eta = -\frac{1}{2} \int_0^\tau d\eta \int_{y+\eta-\tau}^{y-\eta+\tau} Q d\xi = \\ &= -\frac{1}{2} \int_0^\tau [T(y-\eta+\tau, \eta) - T(y+\eta-\tau, \eta)] d\eta \end{aligned} \quad (2.2)$$

Taking (1.9) into account, we obtain the solution in the following form:

in the region *yOGN*

$$u = 0$$

in the region *OGHO*

$$\begin{aligned} u &= \frac{4T_0}{3\beta} \sqrt{\tau} + T_0 y - \frac{T_0 \beta}{2} (\sqrt{1/4\beta^2 + y + \tau} - \sqrt{1/4\beta^2 - y + \tau}) - \\ &- \frac{T_0}{\beta} (\tau - y) A^{1/2}(\tau - y) - \frac{T_0}{\beta} (\tau + y) A^{1/2}(\tau + y) + \frac{T_0}{3\beta} [A^{1/2}(\tau - y) + A^{1/2}(\tau + y)] \end{aligned}$$

in the region *MHGN*

$$\begin{aligned} u &= T_0 \beta \sqrt{1/4\beta^2 - y + \tau} - \frac{T_0}{\beta} (\tau - y) [A^{1/2}(\tau - y) - B^{1/2}(\tau - y)] + \\ &+ \frac{T_0}{3\beta} [A^{1/2}(\tau - y) - B^{1/2}(\tau - y)] \end{aligned}$$

where

$$A(x) = 1/4\beta^2 + x - \beta \sqrt{1/4\beta^2 + x}, \quad B(x) = 1/4\beta^2 + x + \beta \sqrt{1/4\beta^2 + x} \quad (2.3)$$

For the stresses, by formula (1.6), we obtain the following results:

in the region *yOGN*

$$s = 0$$

in the region *OGHO*

$$s = \frac{T_0}{\beta} [A^{1/2} (\tau - y) - A^{1/2} (\tau + y)] - T_0 \left(1 - \frac{y}{\beta \sqrt{\tau}} \right) \quad (2.4)$$

in the region *MHGN*

$$s = \frac{T_0}{\beta} [A^{1/2} (\tau - y) - B^{1/2} (\tau - y)] \quad (2.5)$$

On the bisector $\tau = y$ we will have

$$s = -T_0 + \frac{T_0}{\beta} \sqrt{y} - \frac{T_0}{\beta} A^{1/2} (2y) \quad (y \leq \beta^2), \quad s = -T_0 \quad (y \geq \beta^2) \quad (2.6)$$

Hence it is clear that those lines in the region *MHGN* which are parallel to the principal bisector will be lines of constant displacements, velocities, and stresses.

For the determination of the solution in the region τOM , we have the Cauchy problem:

$$\frac{\partial^2 u}{\partial y^2} = \frac{\partial^2 u}{\partial \tau^2} + Q(y, \tau), \quad u(0, \tau) = \varphi(\tau), \quad u_y(0, \tau) = T_0 \quad (2.7)$$

where $\varphi(\tau)$ is a yet unknown function; the indices y and τ indicate derivatives. By the d'Alembert formula we obtain (Fig. 1)

$$u(P) = \frac{1}{2} \varphi(\tau + y) + \frac{1}{2} \varphi(\tau - y) + T_0 y + \frac{1}{2} \iint_{\Delta DPE} Q(\xi, \eta) d\xi d\eta \quad (2.8)$$

From the condition of continuity of displacement on the bisector $\tau = y$ we find

$$\varphi(\gamma) = -T_0 \gamma - \int_0^\gamma d\eta \int_0^{\gamma-\eta} Q(\xi, \eta) d\xi$$

Substituting this expression into (2.8), we obtain

$$u(y, \tau) = T_0 (y - \tau) + \frac{1}{2} \iint_{\Delta DPE} Q d\xi d\eta - \frac{1}{2} \iint_{\Delta ODC} Q d\xi d\eta - \frac{1}{2} \iint_{\Delta OEK} Q d\xi d\eta$$

Since $Q = \partial T / \partial y$ is independent of y , then, considering the function $Q(y, \tau)$ continued as an even function into the region of negative values of y , the solution can be rewritten in the form

$$u(y, \tau) = T_0 (y - \tau) - \frac{1}{2} \iint_{\Delta FPC} Q d\xi d\eta = T_0 (y - \tau) - \frac{1}{2} \int_0^\tau [T(y + \tau - \eta, \eta) - T(y - \tau + \eta, \eta)] d\eta$$

By formula (1.5) for the stresses, taking account of (1.9), we obtain

in the region τOHL

$$s = \frac{T_0}{\beta} [A^{1/2}(\tau - y) - A^{1/2}(\tau + y)] + \frac{T_0}{\beta} \frac{y}{\sqrt{\tau}} \tag{2.9}$$

in the region LHM

$$s = \frac{T_0}{\beta} [A^{1/2}(\tau - y) - B^{1/2}(\tau - y)] + T_0 \tag{2.10}$$

on the bisector $\tau = y$

$$s = \frac{T_0}{\beta} \sqrt{y} - \frac{T_0}{\beta} A^{1/2}(2y) \quad (y \leq \beta^2), \quad s = 0, \quad (y \geq \beta^2) \tag{2.11}$$

Comparing with (2.6), we obtain the jump in stresses at the shock-wave front $\tau = y$

$$[s] \equiv s(y, y + 0) - s(y, y - 0) = T_0$$

Figure 2 gives the graphs of the variation of stresses with time for $T_0 = 1/2$ at the sections $y = 1$ and $y = 6$. Figure 3 gives the graphs of the dependence of s on the distance from the free face of the bar ahead of and behind the shock-wave front.

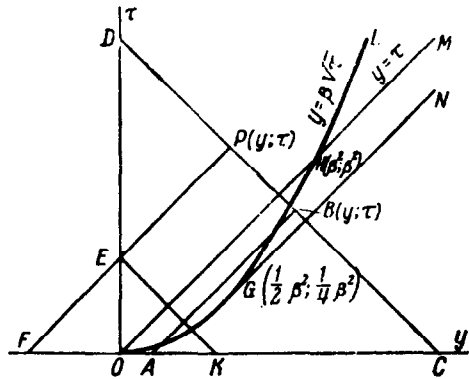


Fig. 1.

3. From these graphs it is clear that when $T_0 = 1$, the stress reaches the elastic limit at the special point O (the origin of coordinates) and on the whole section $y \geq \beta^2$ of the leading face of the shock-wave front, which is a consequence of the fact that the velocity of propagation of heat in the bar is finite. Moreover, this present solution differs essentially from that in [3], which was constructed on the basis of the classical linear equations of heat conduction. When $T_0 > 1$, there arise regions of plastic deformations (1), which are adjacent to the leading side of the shock-wave front and the forms of which are shown schematically in Fig. 4, where (2) is the elastic region.

In the elastic region (where $\tau \leq y$), the earlier solutions (2.4) and (2.5) remain valid. From these formulas and the condition $s = -1$ we find the equation of the elastic-plastic boundary

$$A^{1/2}(\tau + y) - A^{1/2}(\tau - y) = \frac{y}{\sqrt{\tau}} + \beta \frac{1 - T_0}{T_0} \quad (y \leq \beta \sqrt{\tau})$$

$$y = \tau + \frac{\beta^2 T_0^2 - 1}{4 T_0^2} \quad (y \geq \beta \sqrt{\tau}) \quad (3.1)$$

We will find the value $T_0 = T_0^*$ for which the points A and B merge, i.e. starting with which all cross-sections of the bar in the course of time become plastic. Clearly, this takes place (Fig. 3) under the

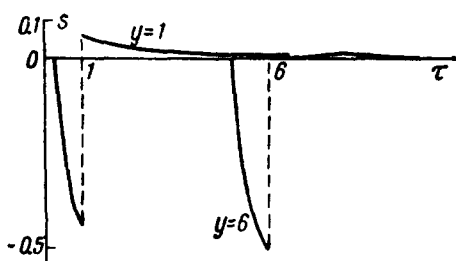


Fig. 2.

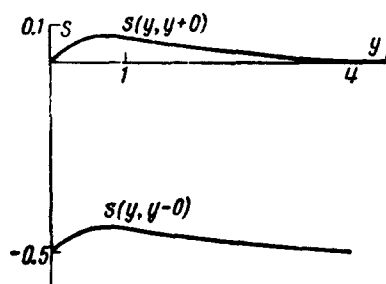


Fig. 3.

condition $\max s(y, y - 0) = -1$. Setting the derivative ds/dy equal to zero, we obtain

$$\sqrt{y} (2\sqrt{1/4\beta^2 + 2y} - \beta) - \sqrt{1/4\beta^2 + 2y} A^{1/2}(2y) = 0, \quad \text{or} \quad (4y - 1/2\beta^2)^2 = 0$$

Hence

$$y = \frac{1}{8} \beta^2, \quad T_0^* = \frac{2\sqrt{2}}{\sqrt{6 - 4\sqrt{2}} + 2\sqrt{2} - 1} \approx \frac{7}{6} \quad (3.2)$$

In the plastic region, for a linear work-hardening material, the stresses are (Fig. 5)

$$\frac{\partial u}{\partial y} = e \equiv e^0 + T, \quad s = q^2 e^0 + q^2 - 1, \quad q^2 = \frac{E_1}{E} \quad (3.3)$$

where E_1 is the modulus of strain hardening. Whence

$$s = q^2 \frac{\partial u}{\partial y} - q^2 T + q^2 - 1 \quad (3.4)$$

From (1.5) and (3.4) we obtain the equation of motion

$$\frac{\partial^2 u}{\partial \tau^2} = q^2 \left(\frac{\partial^2 u}{\partial y^2} - \frac{\partial T}{\partial y} \right) \quad (3.5)$$

This equation can be solved numerically by the method of characteristics. Along the characteristics $dy = \pm qd\tau$ we accordingly have

$$du_\tau = \pm qdu_y - q^2 \frac{T_0}{\beta \sqrt{\tau}} d\tau$$

Integrating these relations, we obtain

$$\begin{aligned} u_\tau &= \pm qu_y - \frac{2q^2 T_0}{\beta} \sqrt{\tau} + C_{1,2} \quad \text{when } T \neq 0 \\ u_\tau &= \pm qu_y - D_{1,2} + C_{1,2} \quad \text{when } T = 0 \end{aligned} \tag{3.6}$$

and then it is easy to find the stresses. The constants $D_{1,2}$ in the last formula can be found from the condition that the velocities and stresses should be continuous along the characteristics, i.e. by requiring equal values of the function $2q^2 T_0 / \beta \sqrt{\tau}$ at the point of intersection of corresponding characteristics with the parabola $y = \beta \sqrt{\tau}$; the constants $C_{1,2}$ can be determined from the values of u_y and u_τ on the elastic-plastic boundary.

The solution which has been constructed for the plastic regions will be unique only for those values of q for which the characteristics $dy = \pm qd\tau$ intersect the elastic-plastic boundary at a single point. This limitation is a consequence of the assumption concerning linear work hardening. The calculations show that for $T_0 \geq 2.5$ the solution is valid for arbitrary values $0 \leq q < 1$.

If the solution is known in the plastic region, then the solution behind the shock-wave front can be constructed in the following manner.

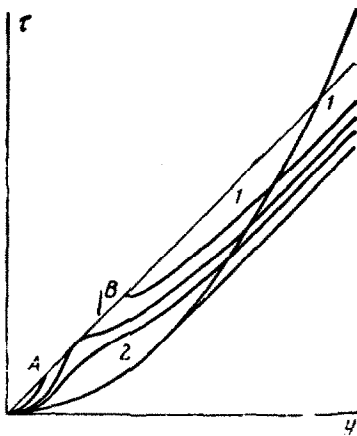


Fig. 4.

Since it is known from the elastic solution that $[s] > 0$, it follows that instantaneous unloading along the line

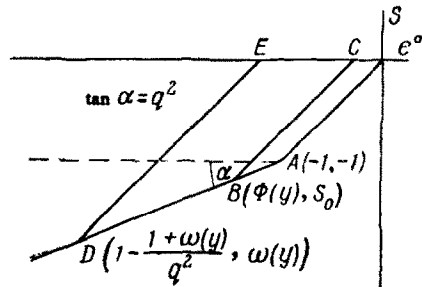


Fig. 5.

BC (Fig. 5) takes place, when passing across the shock-wave front. We

introduce the functions

$$\Phi(y) = u_y(y, y=0) - T(y, y) \equiv e^0(y, y=0)$$

$$\Psi(y) = u_\tau(y, y=0)$$

By formula (3.3), we find (Fig. 5)

$$s_0 = q^2 \Phi(y) + q^2 - 1$$

and the equation of the unloading line BC will be

$$s = e^0 - (1 - q^2) [\Phi(y) + 1]$$

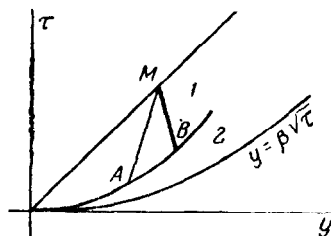


Fig. 6.

Consequently, the equation of state in the region behind the shock-wave can be written as follows

$$s = u_y - T + \alpha(y), \quad \alpha(y) = \begin{cases} (q^2 - 1) [\Phi(y) + 1] & (\Phi(y) \leq -1) \\ 0 & (\Phi(y) \geq -1) \end{cases} \quad (3.7)$$

whereby, when $T > T_0^*$ for arbitrary y

$$\alpha(y) = (q^2 - 1) [\Phi(y) + 1]$$

Thus, in the region $\tau \geq y$ we again obtain a Cauchy problem

$$\frac{\partial^2 u}{\partial y^2} = \frac{\partial^2 u}{\partial \tau^2} + Q_2(y, \tau), \quad Q_2 = T_y - \alpha'(y)$$

$$u(0, \tau) = \varphi(\tau), \quad u_y(0, \tau) = T_0 - \alpha(0) \quad (3.8)$$

where $\varphi(\tau)$ is an as yet unknown function.

We define $\alpha_0 = \alpha(0)$. Along the elastic-plastic boundary (3.1) we have

$$s = -1, \quad T = T_0 \left[1 - \frac{1}{3} A'^{1/2}(\tau + y) + \frac{1}{3} A'^{1/2}(\tau - y) + \frac{1 - T_0}{T_0} \right]$$

When $y, \tau \rightarrow 0$ along (3.1)

$$A \rightarrow 0, \quad T \rightarrow T_0 \left(1 + \frac{1 - T_0}{T_0} \right) = 1$$

Consequently, $u_y = s + T$ tends to $u_0 = 0$.

Ahead of the shock-wave near the origin of coordinates (Fig. 6), by formula (3.6), we have

$$u_y(M) = \frac{u_y(A) + u_y(B)}{2} + \frac{u_\tau(A) - u_\tau(B)}{2a} + \frac{f(A) - f(B)}{2q}, \quad f(\gamma) = \frac{2q^2 T_0}{\beta} \sqrt{\gamma}$$

When $M \rightarrow 0$, we have $u_y \rightarrow 1/2(u_0 + u_0) = 0$, and, consequently,

$$\Phi(0) = -T_0.$$

Similarly, it can be proved that $\Psi(0) = 0$. Thus,

$$\alpha_0 = (1 - q^2)(T_0 - 1) \tag{3.9}$$

The solution of (3.8) has the form

$$u(y, \tau) = \frac{1}{2} \varphi(\tau + y) + \frac{1}{2} \varphi(\tau - y) + \frac{1}{2} \int_{\tau}^{\tau+y} T(y + \tau - \eta, \eta) d\eta + \frac{1}{2} \int_{\tau-y}^{\tau} T(y - \tau + \eta, \eta) d\eta - \int_0^y \alpha(y) dy \tag{3.10}$$

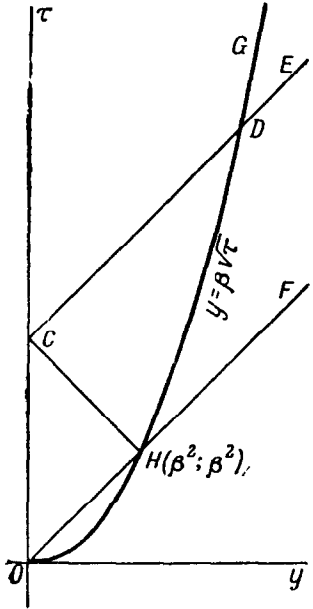


Fig. 7.

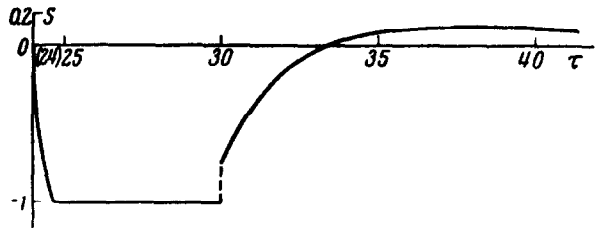


Fig. 8.

From the condition that u is continuous when $\tau = y$, we find

$$\varphi(\gamma) = -\varphi(0) + 2 \int_0^{1/2\gamma} \alpha(y) dy - \int_0^{1/2\gamma} T(y, y) dy - \int_{1/2\gamma}^{\gamma} T(\gamma - y, y) dy + 2U(1/2\gamma) \tag{3.11}$$

where $U(y) = u(y, y - 0)$. From (1.9), (2.6), (3.10), (3.11), and noting that

$$dU/dy = u_y(y, y - 0) + u_\tau(y, y - 0) = \Phi(y) + \Psi(y) + T(y, y)$$

we find the stresses in the corresponding regions

$$s = F(y, \tau) - \frac{T_0}{\beta \sqrt{2}} (\sqrt{\tau + y} - \sqrt{\tau - y}) - T(y, \tau) \tag{OHCO} \tag{3.12}$$

$$s = F(y, \tau) + \frac{T_0}{\beta \sqrt{2}} \sqrt{\tau - y} - \frac{T_0}{\beta} A^{1/2} (\tau + y) - T(y, \tau) \tag{CHDC} \tag{3.13}$$

$$s = F(y, \tau) + \frac{T_0}{\beta \sqrt{2}} \sqrt{\tau - y} - \frac{T_0}{\beta} B^{1/2} (\tau - y) \tag{EDHF} \tag{3.14}$$

$$s = F(y, \tau) - \frac{T_0}{\beta} [A^{1/2}(\tau + y) - A^{1/2}(\tau - y)] - T(y, \tau) \quad (\tau CDG) \quad (3.15)$$

$$s = F(y, \tau) - \frac{T_0}{\beta} [B^{1/2}(\tau - y) - A^{1/2}(\tau - y)] \quad (GDE) \quad (3.16)$$

where

$$F(y, \tau) = \frac{1}{2} \alpha \left(\frac{\tau + y}{2} \right) - \frac{1}{2} \alpha \left(\frac{\tau - y}{2} \right) + \frac{1}{2} \Phi \left(\frac{\tau + y}{2} \right) - \frac{1}{2} \Phi \left(\frac{\tau - y}{2} \right) + \quad (3.17)$$

$$+ \frac{1}{2} \Psi \left(\frac{\tau + y}{2} \right) - \frac{1}{2} \Psi \left(\frac{\tau - y}{2} \right) + \frac{1}{2} T \left(\frac{\tau + y}{2}, \frac{\tau + y}{2} \right) - \frac{1}{2} T \left(\frac{\tau - y}{2}, \frac{\tau - y}{2} \right) + T_0$$

From (3.4), (3.12) and (3.14) we find

$$[s] = \frac{1}{2} \alpha(y) + \left(\frac{1}{2} - q^2 \right) \Phi(y) + \frac{1}{2} \Psi(y) + \frac{1}{2} T(y, y) - \frac{1}{2} \alpha_0 + 1 - q^2$$

In that part of the plastic region, in which the characteristics $dy = \pm q d\tau$ do not pass through the region $T > 0$, by (3.6), we have $u_y = -1$, $u_\tau = 1$. Hence, for sufficiently large y

$$\alpha(y) = (q^2 - 1) [\Phi(y) + 1] = (q^2 - 1) (u_y - T + 1) = 0$$

$$[s] = 1 - \frac{1}{2} (1 - q^2) (T_0 - 1)$$

When $T_0 > (3 - q^2)/(1 - q^2)$, the jump in the stresses on the shock-wave becomes negative and the obtained solution behind the shock-wave front is no longer valid, since the equation of state (3.7), in this case, is not valid for all values of y . The solution for $T_0 > (3 - q^2)/(1 - q^2)$ can be constructed in the following way.

First of all we observe that, in this case, the stress exceeds the elastic limit also at the rear of the shock-wave front.

Taking the solution sought to be unique, we will assume that only the rear $\tau = y + 0$ of the wave front remains plastic and that there is immediate unloading behind it. We introduce the function $\omega(y) = s(y, y = 0)$. Then the equation of the line of unloading DE (Fig. 5) will be

$$s = e^0 + \omega(y) - \frac{\omega(y)}{q^2} + 1 - \frac{1}{q^2}$$

and the equation of state can be written down in the form

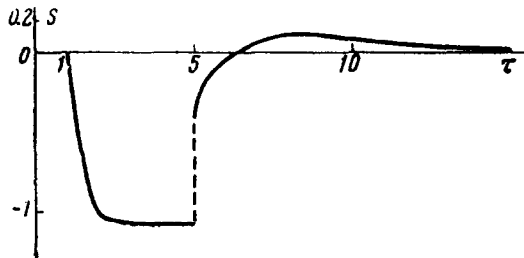


Fig. 9.

$$s = u_y - T + \Omega(y), \quad \Omega(y) = \begin{cases} \alpha(y) & [s] \geq 0 \\ (q^2 - 1) / q^2 [\omega(y) + 1], & [s] \leq 0 \end{cases} \quad (3.18)$$

Moreover, for sufficiently small y and τ , $\Omega(y) = \alpha(y)$ always, so that $\lim s(y, y + 0) = 0$, $\lim s(y, y - 0) = -T_0$ as $y \rightarrow 0$ and $[s]_{y=0} = T_0$. Consequently, $\Omega(0) = \alpha_0$.

When $\tau \geq y$, the solution (3.12) to (3.17), in which $\alpha(y)$ must be replaced by $\Omega(y)$, will now be valid. The function $\omega(y)$ can be obtained from the condition $s(y, y + 0) = \omega(y)$

$$\omega(y) = \frac{q^2}{1 + q^2} [\Phi(y) + \Psi(y) + T(y, y)] - \frac{\alpha_0 q^2 - q^2 + 1}{1 + q^2} \quad (3.19)$$

It is easily verified that $s_{\tau}(y, y + 0) = \infty$, i.e. the assumption that there is instantaneous unloading after the passage of the wave front is fulfilled.

Figures 8 and 9 show the graphs (s, τ) at the sections $y = 5$, and $y = 30$ of the bar for $T_0 = 3$, $q = 1/2$, which graphs were obtained as the result of numerical computations.

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